# An introduction to insurance pricing models and in particular treebased machine learning models

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#### Why Classifying Risks?

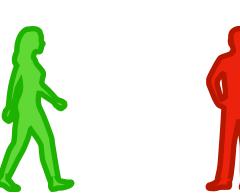
E [cost   Female] E [cost   Male]	50 150			
E [cost]	100			
		Insurer A $= \mathbb{E}[Cost   Sex]$		rer B  E[Cost]
	SEG	EMENTATION	MUTU	ALISATION

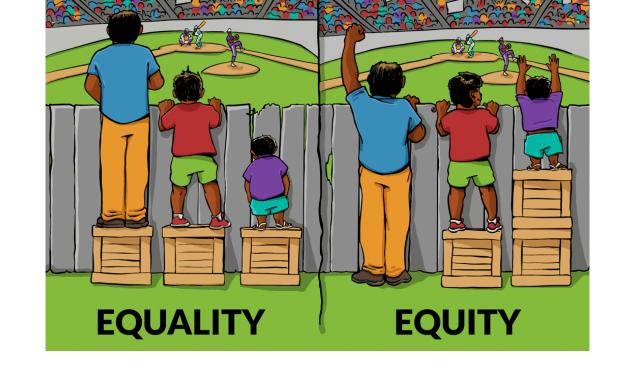


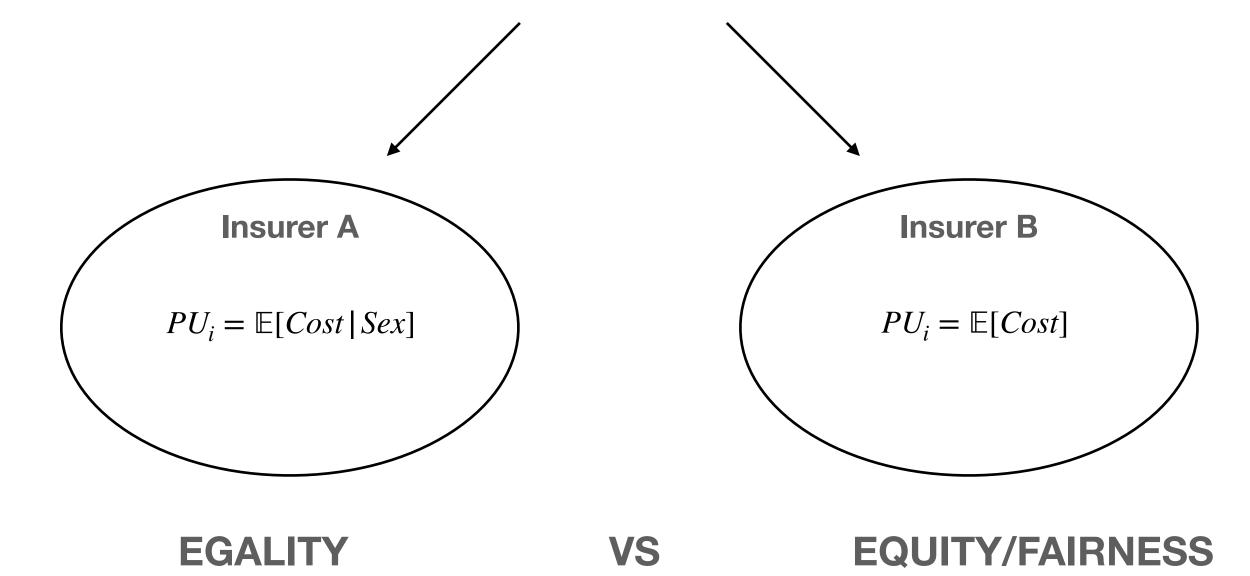
#### Why Classifying Risks?

#### Philosophical point of view

50
150
100









### Why Classifying Risks?

#### Insurer's point of view

	50	50 100	150 100
E [cost   Male]	150		
	100		
		Insurer A $I_i = \mathbb{E}[Cost   Sex]$	Insurer B $PU_i = \mathbb{E}[Cost]$ ADVERSE SELECTION PHENOMENON



Let  $Y \in \mathbb{R}^m$  be a response vector and  $\mathbf{X} \in \mathbb{R}^{m \times p}$  a vector of features

The aim of actuarial ratemaking is to evaluate the pure premium as accurately as possible. The target is thus the conditional expectation:

$$\mu(\mathbf{X}) = \mathbb{E}[Y|\mathbf{X}]$$

$$\mathbf{\hat{\mu}}(\mathbf{X})$$
Generally unknown 
$$\hat{\mu}(\mathbf{X})$$

Lot of data Lot of features





#### **Dataset**

$$\begin{pmatrix} y^{(1)} & x_1^{(1)} & x_2^{(1)} & x_3^{(1)} & \cdots & x_p^{(1)} \\ y^{(2)} & x_1^{(2)} & x_2^{(2)} & x_3^{(2)} & \cdots & x_p^{(2)} \\ \vdots & \cdots & \cdots & \vdots & \vdots \\ y^{(n)} & x_1^{(n)} & x_2^{(n)} & x_3^{(n)} & \cdots & x_p^{(n)} \end{pmatrix}$$

#### **Target Vector**

$$\mathbf{Y} = \begin{bmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(n)} \end{bmatrix}$$

#### **Features Matrix**

$$\mathbf{X} = \begin{pmatrix} x_1^{(1)} & \cdots & x_p^{(1)} \\ \vdots & \ddots & \vdots \\ x_1^{(n)} & \cdots & x_p^{(n)} \end{pmatrix}$$



#### Goal

 $\hat{\pi}: \mathbf{X} \to Y$  that minimizes the expectation of some loss function  $L(Y, \hat{\pi})$ 

over the joint distribution of all  $(Y, \mathbf{X})$  – values, i.e;

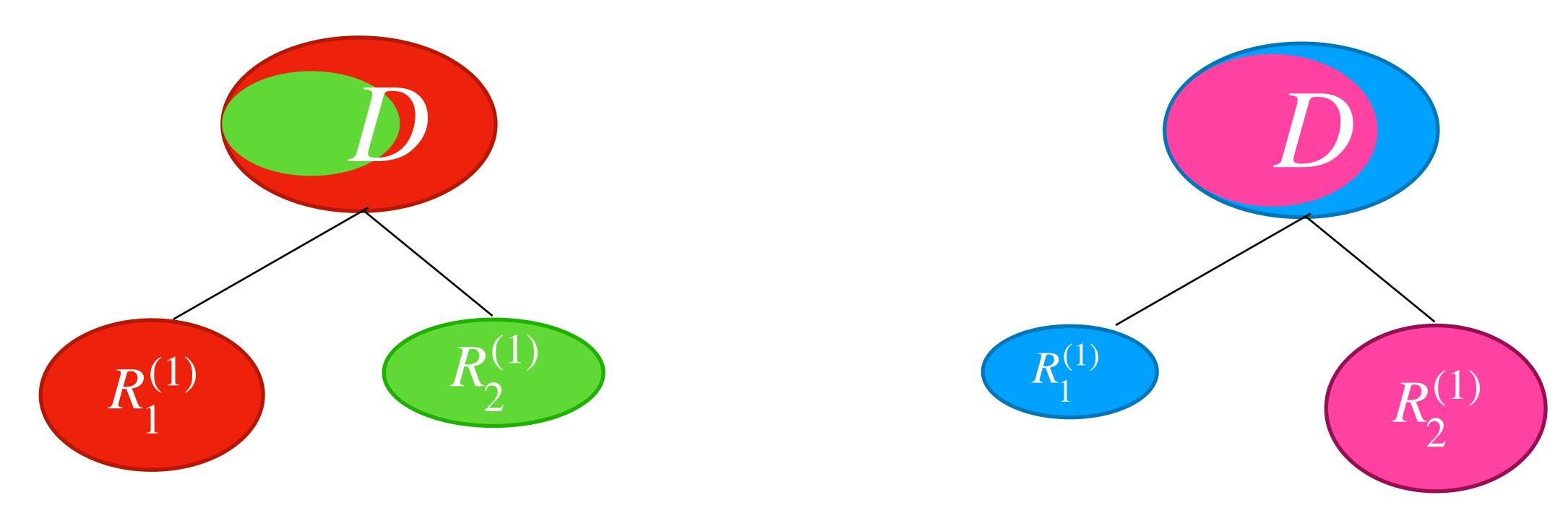
$$\hat{\pi}(\mathbf{X}) = \hat{E}[Y | \mathbf{X}] = \arg\min_{\pi(\mathbf{X})} E[L(Y, \pi(\mathbf{X}))]$$

$$\approx \arg\min_{\pi(\mathbf{x})} \frac{1}{n} \sum_{i=1}^{n} L(y_i, \pi(\mathbf{x}_i)) = \arg\min_{\pi(\mathbf{x})} \sum_{i=1}^{n} L(y_i, \pi(\mathbf{x}_i))$$



#### Idea

To begin, the idea is to partition the predictor space into two regions:  $R_1^{(1)}$  and  $R_2^{(1)}$ 



How to choose  $R_1^{(1)}$  and  $R_2^{(1)}$ ?

Wich prediction in each of  $R_1^{(1)}$  and  $R_2^{(1)}$ ?



#### Idea

Training set =  $\{(y_i, \mathbf{x}_i); i = 1, \dots, n\}$  denoted **D**.

Search every distinct value of every predictor to find the predictor and split value that partitions the predictor space into two regions:

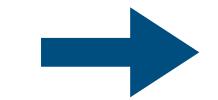
$$R_1^{(1)}$$
 and  $R_2^{(1)}$  such that

$$\overline{c}_1^{(1)} = \text{ave}\left(y_i \mid \mathbf{x}_i \in R_1^{(1)}\right)$$

$$\sum_{i=1}^{n} L(y_i, \pi(\mathbf{x}_i)) = \sum_{i: \mathbf{x}_i \in R_1^{(1)}} L(y_i, \overline{c}_1^{(1)}) + \sum_{i: \mathbf{x}_i \in R_2^{(1)}} L(y_i, \overline{c}_2^{(1)})$$

$$\overline{c}_2^{(1)} = \text{ave}\left(y_i | \mathbf{x}_i \in R_2^{(1)}\right)$$

$$\pi(\mathbf{x}_i) = \overline{c}_1^{(1)} I_{\{\mathbf{x}_i \in R_1^{(1)}\}} + \overline{c}_2^{(1)} I_{\{\mathbf{x}_i \in R_2^{(1)}\}}$$



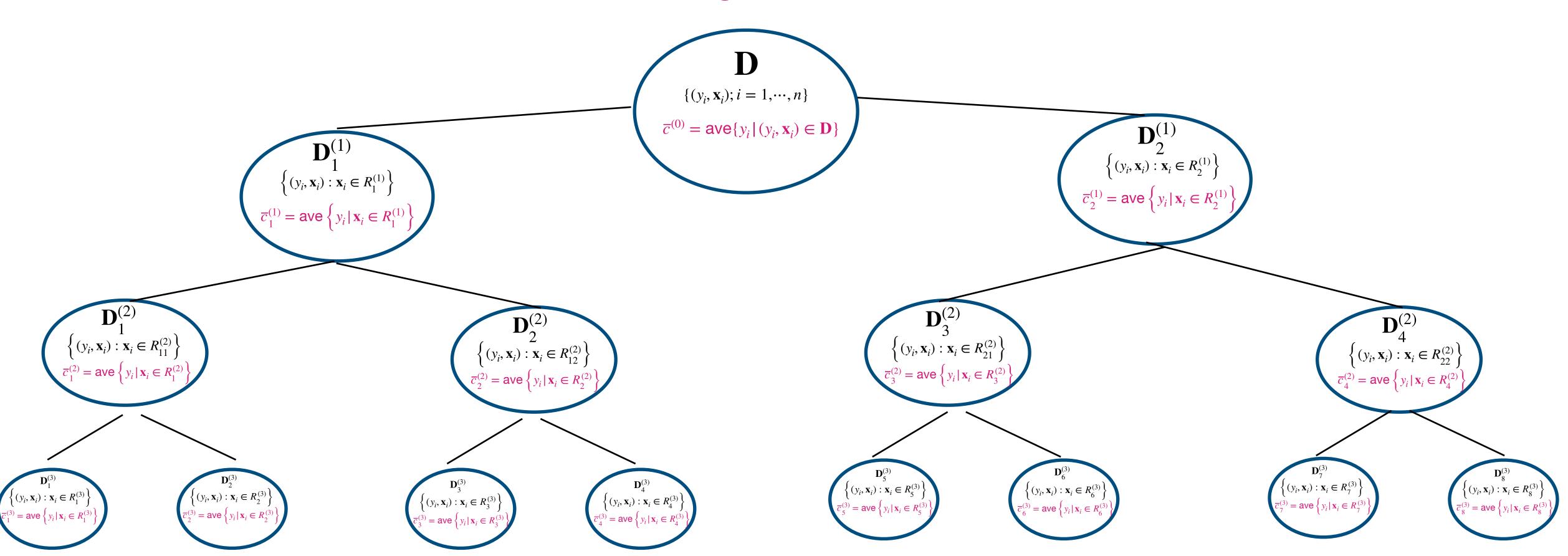
The training set  $\mathbf{D}$  is then partitioned into two groups  $\mathbf{D}^{(1)}$  and  $\mathbf{D}^{(2)}$ , where

$$\mathbf{D}^{(1)} = \left\{ (y_i, \mathbf{x}_i) : \mathbf{x}_i \in R_1^{(1)} \right\}$$

$$\mathbf{D}^{(2)} = \left\{ (y_i, \mathbf{x}_i) : \mathbf{x}_i \in R_2^{(1)} \right\}$$



#### **Algorithm**



$$\hat{\pi}(\mathbf{x}) = \sum_{i=1}^{M} \hat{\overline{c}}_{m} I_{\{\mathbf{x} \in R_{m}\}}$$

Here 
$$M = 2^3 = 8$$



#### **Algorithm**

Repeat the previous step within each of groups  $\mathbf{D}^{(1)}$  and  $\mathbf{D}^{(2)}$  and so on

#### Stop

- When the number of samples in the split falls below some threshold
- When the depth of the tree reached a certain limit
- When the improvement in the loss function becomes too small
- Pruning (with complexity parameter)

. . .

$$\hat{\pi}_{tree}(\mathbf{x}) = \sum_{m=1}^{M} \hat{\overline{c}}_m I_{\{\mathbf{x} \in R_m\}}$$



#### **Advantages & Disadvantages**

#### Advantages

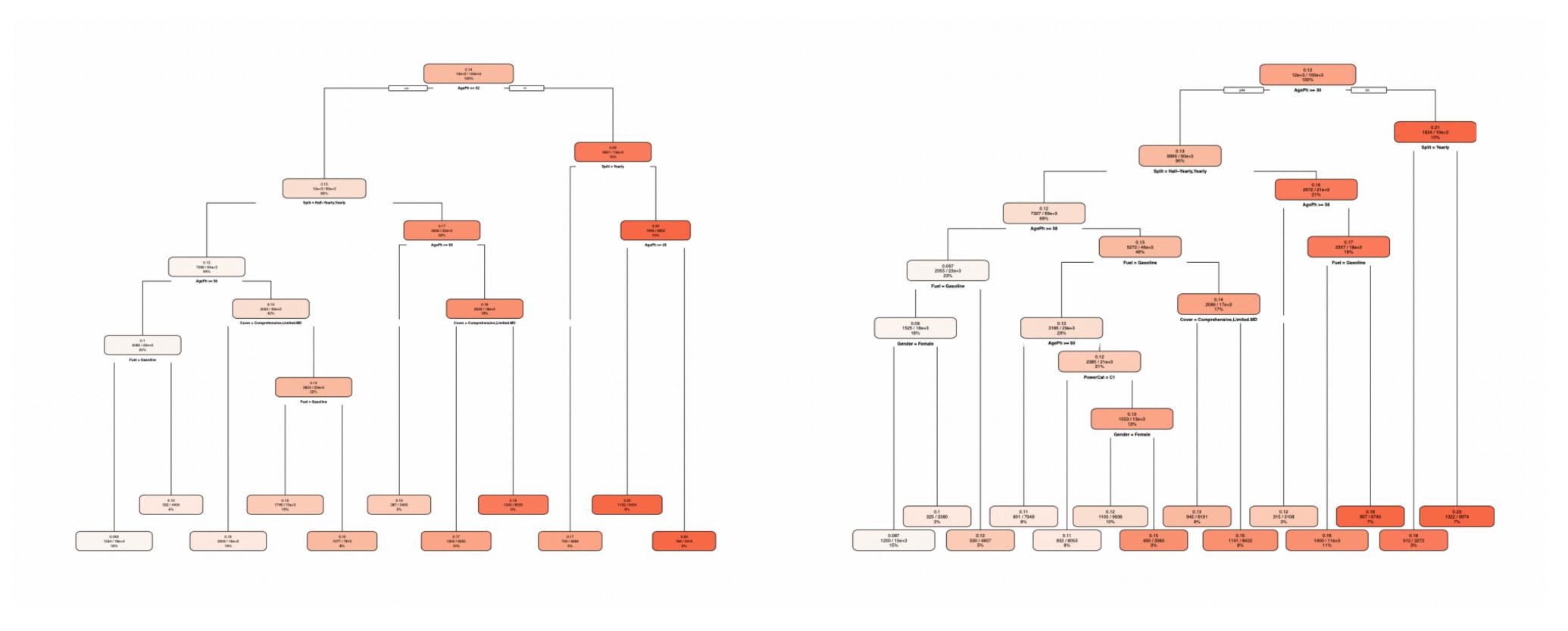
- Easy to interpret
- Intuitively, the most important predictors are those that appear
  - → Higher in the tree;
  - → Several times in the tree.
- Do not require to specify the form of the regression function (Non-parametric regression)



#### Disadvantages

- The final tree can be very large and overfit the training set
- Instability of the Model (slight changes in the data can drastically change the structure of the tree).
- Finite number of possible predicted outcomes (determined by number of terminal nodes).
- Partition the data in rectangular regions of the predictor space (not optimal predictive performance)

### **Advantages & Disadvantages**



data1 = data[1:100000,]

data2 = data[10000:110000,]



# Bagging & Random Forest



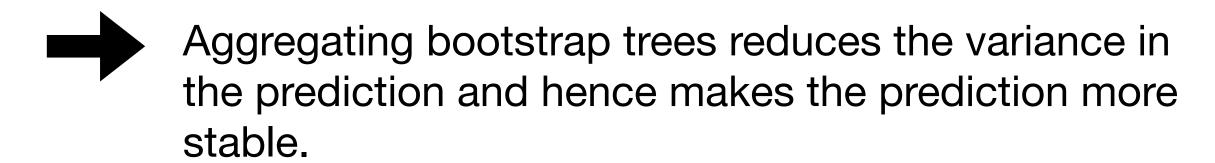
# Bagging & Random Forest

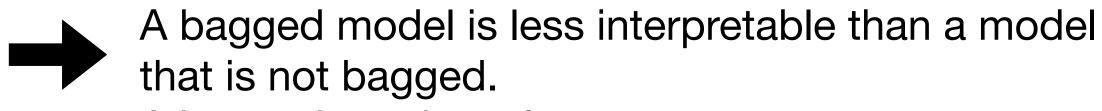
#### **Bagging**

For t = 1 to T:

- 1) Generate a Bootstrap D\_t sample of the original data
- 2) Fit a tree on this Sample D\_t
- 3) Give a prediction :  $\hat{\pi}(\mathbf{x})$

$$\hat{\pi}_{bag}(\mathbf{x}) = \frac{1}{T} \sum_{i=1}^{T} \hat{\pi}_{t}(\mathbf{x})$$





A bagged tree is no longer a tree.

#### **Random Forest**

For t = 1 to T:

- 1) Generate a Bootstrap D\_t sample of the original data
- 2) Fit a tree such that:

For each node:

- Select randomly m predictors
- Choose de best predict amoung theses m predictors
- Split the node into two daughters node
- 3) Give a prediction:

$$\hat{\pi}_{rf}(\mathbf{x}) = \frac{1}{T} \sum_{i=1}^{T} \hat{\pi}_{t}(\mathbf{x})$$

Reducing m reduce the correlation between any pair of trees Reduce the variance of  $\hat{\pi}_{rf}(\mathbf{x})$ 





#### **Boosting Methods**

Several trees are also used. But this is not the same philosophy as bagging or RF.

Each tree will explain what is not yet explained.

Boosting Methods combining many weak rules to approximate

A weak learner is a learning algorithm which is slightly better than random guessing.

A weak learner can be constructed by a small regression tree!



#### **Additive models & Boosting**

The standard linear regression model assumes a linear form for the conditional expectation  $E[y | \mathbf{x}]$ 

$$E[y \mid \mathbf{x}] \approx \hat{\pi}(\mathbf{x}) = \beta_0 + \sum_{j=1}^p \beta_j x_j$$

An additive model extends the linear model, by assuming an additive predictor of the form:

$$E[y \mid \mathbf{x}] \approx \hat{\pi}(\mathbf{x}) = \sum_{j=1}^{p} f_j(x_j)$$

The additive model can be generalized by considering functions of potentially all the inputs variables

$$E[y \mid \mathbf{x}] \approx \hat{\pi}(\mathbf{x}) = \sum_{t=1}^{T} f_t(\mathbf{x}) = \sum_{t=1}^{T} \beta_{t,a_t} h(a_t, \mathbf{x})$$

Estimation of the parameters amounts to solve

$$\min_{\{eta_{t,\mathbf{a}_t},\mathbf{a}_t\}_1^T} \sum_{i=1}^n L\left(y_i,\sum_{t=1}^T eta_{t,\mathbf{a}_t} h(oldsymbol{x}_i;\mathbf{a}_t)
ight).$$



# ULB

#### **Boosting**

#### **Boosting**

Initialize  $\pi_0(\mathbf{x}) = 0$  (for example)

For t = 1 to T, do

1) Estimate  $\beta_{t,\mathbf{a}_t}$  and  $\mathbf{a}_t$  by minimizing:

$$\sum_{i=1}^{n} L(y_i, \pi_{t-1}(\mathbf{x}_i) + \beta_{t,\mathbf{a}_t} h(\mathbf{x}_i, \mathbf{a}_t))$$

2) Update  $\pi(\mathbf{x}) = \pi_{t-1} + \beta_{t,\mathbf{a}_t} h(\mathbf{x}_t, \mathbf{a}_t)$ 

#### Remark

If loss function = squared error

$$\sum_{i=1}^{n} L(y_i, \pi_{t-1}(\mathbf{x}_i) + \beta_{t,\mathbf{a}_t} h(\mathbf{x}_i, \mathbf{a}_t)) = \left(\underbrace{y_i - \pi_{t-1}(\mathbf{x}_i)}_{r_{i,t-1}} - \beta_{t,\mathbf{a}_t} h(\mathbf{x}_i, \mathbf{a}_t)\right)^2$$

 $r_{i,t-1}$  equals the residuals for observation i at the iteration t-1

Output :  $\hat{\pi}(\mathbf{x}) = \pi_T(\mathbf{x})$ 

# ULB

#### **Boosting**

#### **Boosting**

Initialize  $\pi_0(\mathbf{x}) = 0$  (for example)

For t = 1 to T, do

1) Estimate  $\beta_{t,\mathbf{a}_t}$  and  $\mathbf{a}_t$  by minimizing :

Solution to step (2.1) in Algorithm 1 can be difficult to obtain in some cases.

$$\sum_{i=1}^{n} L(y_i, \pi_{t-1}(\mathbf{x}_i) + \beta_{t,\mathbf{a}_t} h(\mathbf{x}_i, \mathbf{a}_t))$$

2) Update  $\pi(\mathbf{x}) = \pi_{t-1} + \beta_{t,\mathbf{a}_t} h(\mathbf{x}_i, \mathbf{a}_t)$ 

The gradient boosting algorithm aims to solve this issue by using a two-step procedure for step (2.1).

Output :  $\hat{\pi}(\mathbf{x}) = \pi_T(\mathbf{x})$ 

#### **Gradient Boosting Method**

#### **Boosting**

Initialize  $\pi_0(\mathbf{x}) = 0$  (for example)

For t = 1 to T, do

1) Estimate  $\beta_{t,\mathbf{a}_t}$  and  $\mathbf{a}_t$  by minimizing :

$$\sum_{i=1}^{n} L(y_i, \pi_{t-1}(\mathbf{x}_i) + \beta_{t,\mathbf{a}_t} h(\mathbf{x}_i, \mathbf{a}_t))$$

2) Update  $\pi(\mathbf{x}) = \pi_{t-1} + \beta_{t,\mathbf{a}_t} h(\mathbf{x}_i, \mathbf{a}_t)$ 

Output :  $\hat{\pi}(\mathbf{x}) = \pi_T(\mathbf{x})$ 

#### **Gradient Boosting Method**

Initialize 
$$\pi_0(\mathbf{x}) = \arg\min_{\beta} \sum_{i=1}^n L(y_i, \beta)$$
  
For  $t = 1$  to  $T$ , do

1) Estimate the negative gradients i.e the pseudo-residuals

$$r_i = \frac{\partial L(y_i, \pi(\mathbf{x}_i))}{\partial \pi(\mathbf{x}_i)} \Big|_{\pi(\mathbf{x}_i) = \pi_{t-1}(\mathbf{x}_i)} i = 1, \dots, n$$

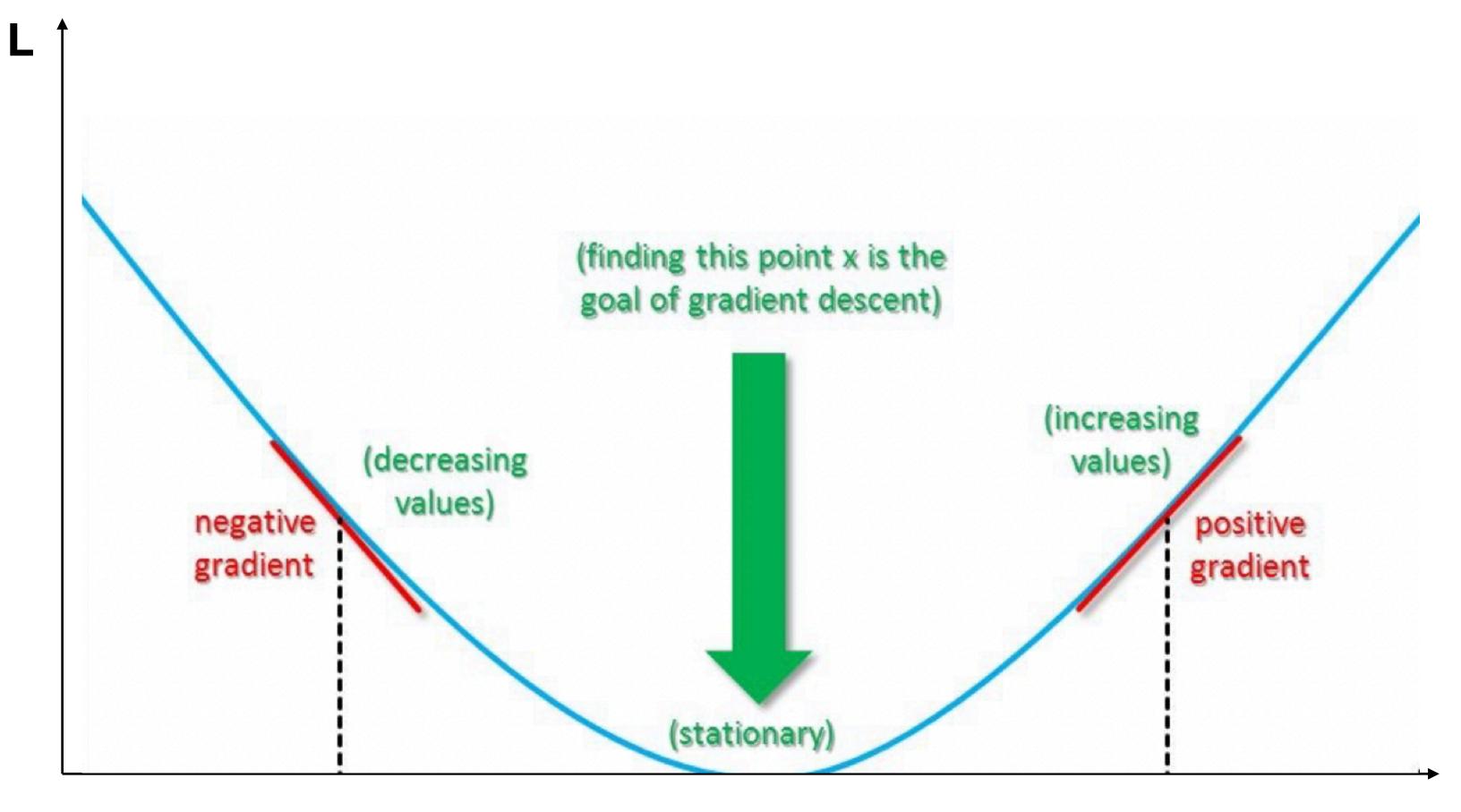
Fit  $h(\mathbf{x}_i, \mathbf{a}_t)$  to  $r_i$  to get  $\mathbf{a}_t$ 

Estimate 
$$\beta_{t,\mathbf{a}_t}$$
 and  $\mathbf{a}_t$  by minimizing: 
$$\sum_{i=1}^n L(y_i, \pi_{t-1}(\mathbf{x}_i)) + \beta_{t,\mathbf{a}_t} h(\mathbf{x}_i, \mathbf{a}_t)$$

2) Update  $\pi(\mathbf{x}) = \pi_{t-1} + \beta_{t,\mathbf{a}_t} h(\mathbf{x}_t, \mathbf{a}_t)$ 

Output : 
$$\hat{\pi}(\mathbf{x}) = \pi_T(\mathbf{x})$$

#### **Gradient Boosting Method**





# Adaptive Boosting Trees (ABT)



# BOOSTING COST-COMPLEXITY PRUNED TREES ON TWEEDIE RESPONSES: THE ABT MACHINE FOR INSURANCE RATEMAKING

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## Adaptive Boosting Trees

#### **Tweedie family**

	Type	Name
$\xi < 0$	Continuous	-
$\xi = 0$	Continuous	Normal
$0 < \xi < 1$	Non existing	-
$\xi = 1$	Discrete	Poisson
$1 < \xi < 2$	Mixed, non-negative	Compound Poisson sums
		with Gamma-distributed severities
$\xi = 2$	Continuous, positive	Gamma
$2 < \xi < 3$	Continuous, positive	_
$\xi = 3$	Continuous, positive	Inverse Gaussian
$\xi > 3$	Continuous, positive	_

Tweedie deviance loss function is given by

$$L(y,\widehat{\mu}(\boldsymbol{x})) = \begin{cases} (y - \widehat{\mu}(\boldsymbol{x}))^2 \text{ for } \xi = 0\\ 2\left(y \ln \frac{y}{\widehat{\mu}(\boldsymbol{x})} - (y - \widehat{\mu}(\boldsymbol{x}))\right) \text{ for } \xi = 1\\ 2\left(-\ln \frac{y}{\widehat{\mu}(\boldsymbol{x})} + \frac{y}{\widehat{\mu}(\boldsymbol{x})} - 1\right) \text{ for } \xi = 2\\ 2\left(\frac{\max\{y,0\}^{2-\xi}}{(1-\xi)(2-\xi)} - \frac{y\widehat{\mu}(\boldsymbol{x})^{1-\xi}}{1-\xi} + \frac{\widehat{\mu}(\boldsymbol{x})^{2-\xi}}{2-\xi}\right) \text{ for } \xi > 1 \text{ and } \xi \neq 2. \end{cases}$$



## Adaptive Boosting Trees

#### Idea

Instead of allowing for trees with constant interaction depth at each iteration

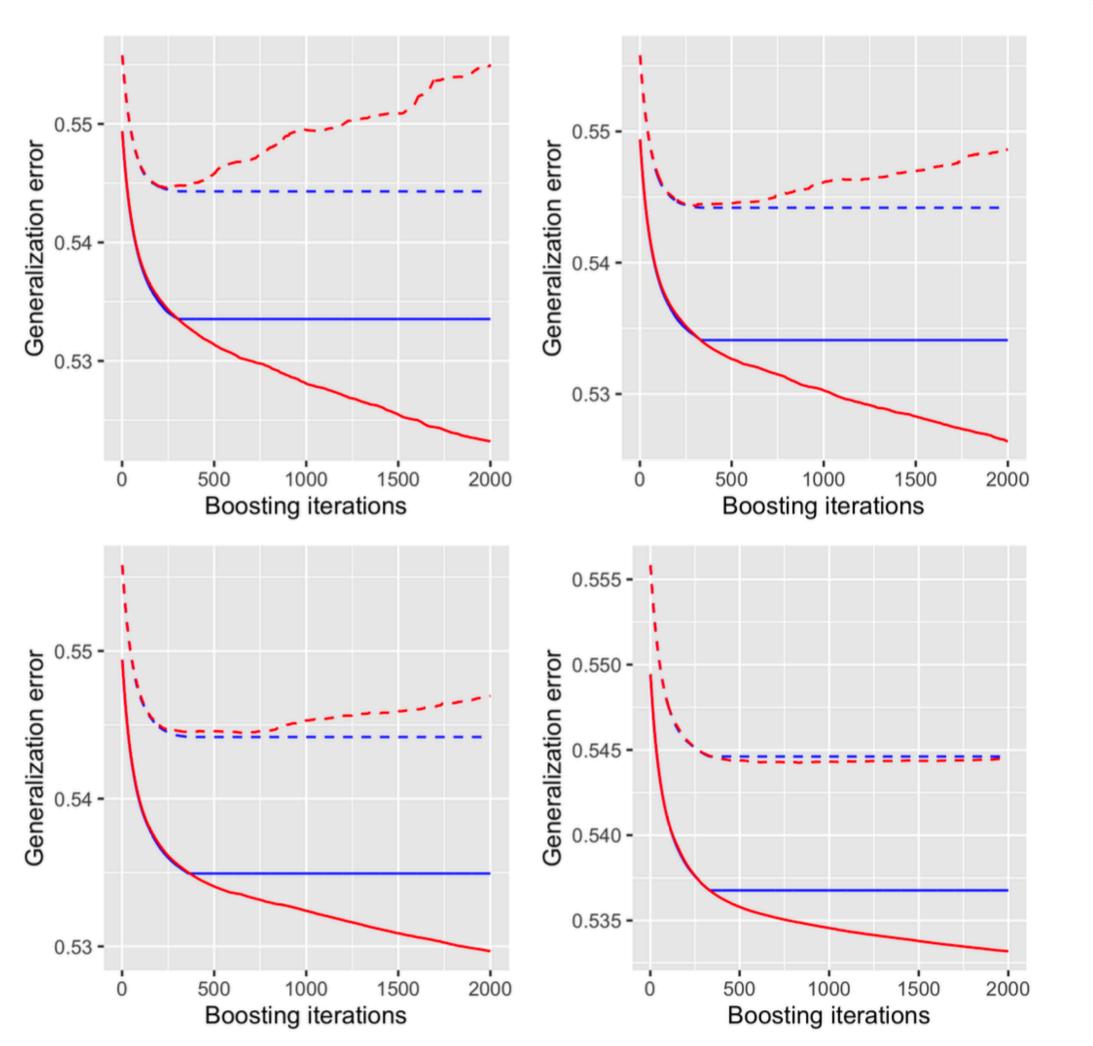
Let the complexity of the newly added tree adapt to the structure remaining to be learned from the data.

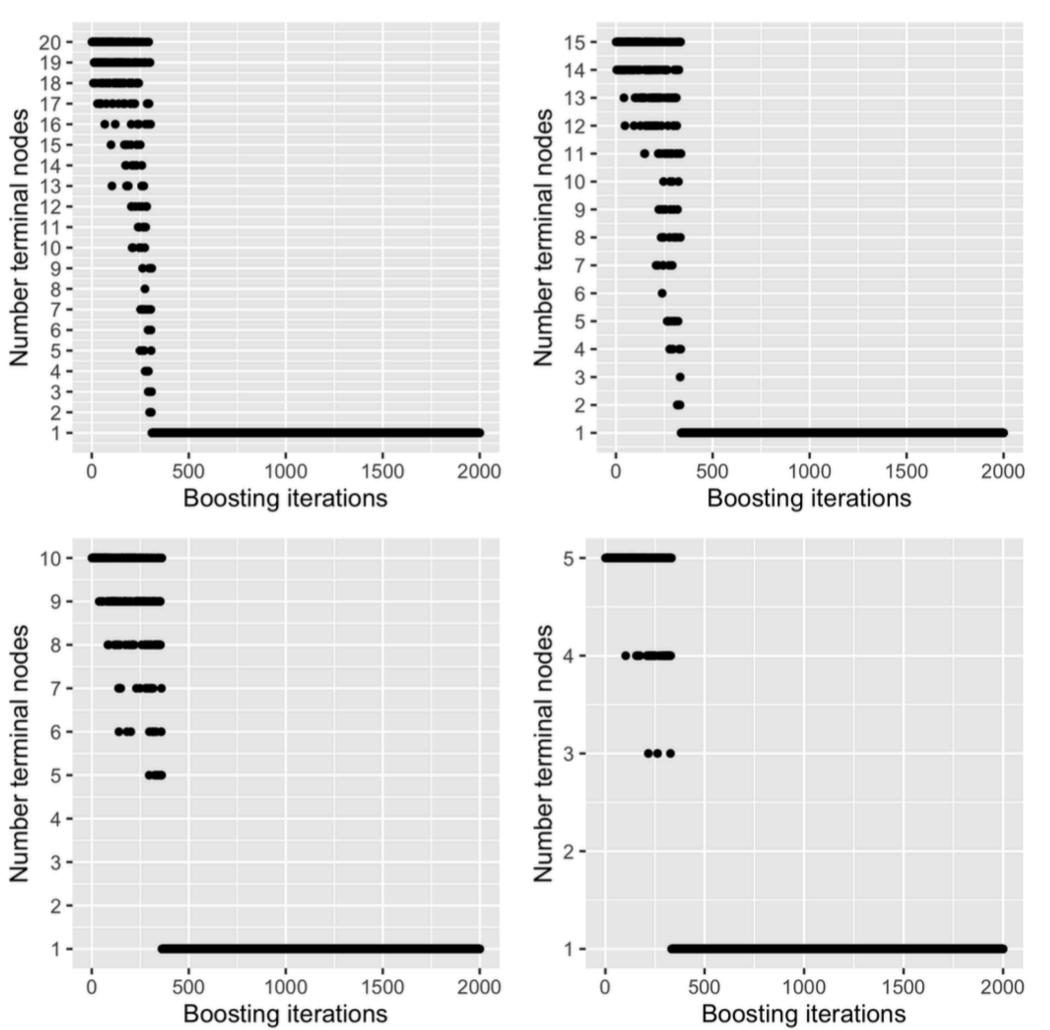
- Larger trees are fitted at earlier stages and they progressively simplify until reducing to the single-node tree where the ABT machine stops.
- The stopping criterion is thus built within the ABT algorithm and no computationally- intensive cross validation step is needed.
- This adaptive boosting algorithm enables to reduce overfitting



# Adaptive Boosting Trees

#### Idea







# Fairness in Machine Learning



# The Fairness of Machine Learning in Insurance: New Rags for an Old Man?

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#### May 2022

#### Abstract

Since the beginning of their history, insurers have been known to use data to classify and price risks. As such, they were confronted early on with the problem of fairness and discrimination associated with data. This issue is becoming increasingly important with access to more granular and behavioural data, and is evolving to reflect current technologies and societal concerns. By looking into earlier debates on discrimination, we show that some algorithmic biases are a renewed version of older ones, while others show a reversal of the previous order. Paradoxically, while the insurance practice has not deeply changed nor are most of these biases new, the machine learning era still deeply shakes the conception of insurance fairness.

"Technology is neither good nor bad; nor is it neutral" [Kranzberg, 1986]



# Thanks a lot for your attention!



# Bibliography

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Julien Trufin

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« The fairness of machine learning in Insurance : New rags for an old man? » Laurence Barry, Arthur Charpentier